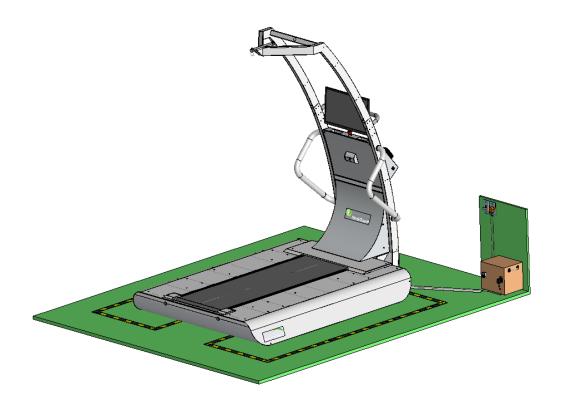


BalanceTutorTM Technical Specification

July 2025



BalanceTutor a dynamic and static postural control trainer

Tel: (972)-9-8637477 Fax: (972)-9-8852935 1 Nirim, Tnuvot, Israel. Zip: 4283000, PO Box: 190 Page 1 of 6 www.meditouch.co.il info@meditouch.co.il

DO-15-01-01



This technical specification covers all critical components and physical elements for the following MediTouch product:

BalanceTutor BT100

The BalanceTutor dynamic and static postural control trainer tested to IEC medical standards for electrical safety. It is a Class I, Type BF device.

Type BF Medical Equipment





IEC 60601-1-1 compliant IEC 60601-1-2 compliant

IPX-0

Date	Change description	Written by	Ver.
01 Jan 2014	Initial version	Ziv K.	140101
13 Mar 2016	US ratings clarifications	Ziv K.	160313
23 Jun 2016	Voltage supply modification, OS change from Win7Pro to Win7Emb (WS7E), Transformer change from 2→2.3 kVA, Nameplate	Ziv K.	160623
	label, Lanyard addition, Wireless Interfaces, and other minor updates.		
13 Sep 2016	Adding sensors sample rates, Change Bluetooth type from 2.0 to 4.0.	Ziv K.	160913
25 Oct 2016	Update Storage Temperature parameter, Adding SPL measure.	Ziv K.	161025
19 Jan 2017	Adding: Power consumption, warnings remarks	Ziv K.	170119
28 Jun 2017	Adding: Wireless sensors Service Time	Ziv K.	170628
06 Sep 2017	Updating product and shipping box weight	Ziv K.	170906
22 May 2018	Updating 3 Phase ratings	Ziv K.	180522
02 Oct 2018	Value conversion corrections (km/h to m/s), in treadmill perturbation parameter section. Update distance of Safety Stop Switch.	Ziv K.	181002
30 Dec 2018	Changes: Power Ratings, Computer OS, Product Label, Warnings modifications.	Ziv K.	181230
21 Jan 2020	Changes: effective running belt length from 140 to 156cm, images update, crate size.	Ziv K.	200121
03 Feb 2021	Adding: Camera, Remote control, Harnesses. Upgrading: BoxPC to ARK1551, Win10 IOT 2019, Changing: Patient screen and holder	Ziv K.	210203
21 Jun 2022	Adding: MD logo at 2 nd page, updating name plate label, Changing company address	Ziv K.	220621
12 Oct 2023	Adding: S/N structure. Changes: Model Number from BT100 to HMBT100A, Name plate label	Ziv K.	231012
10 Nov 2024	Adding: Running belt area and Power consumption of Stand-by mode	Ziv K.	241110
21 July 2025	Changes: Name Plate Label. Adding: Software regulation	Alan W. Ziv K.	250721

E&EO

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PARAMETER	DESCRIPTION

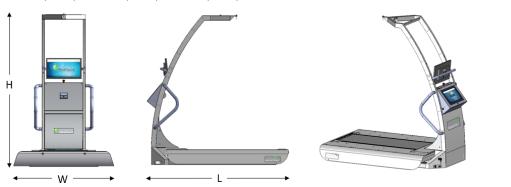
BalanceTutor Product name

Product model HMBT100A

Order P/N HMBT100A

Applications Balance and gait training. Instrumented biomechanical treadmill for research.

Overall dimensions L: 233 cm (91.73") W: 161 cm (63.38") H: 245 cm (96.45")



Effective running belt

surface

Length: 156 cm (61.5") Width: 56 cm (22")

Shock load reduction for the joints

Belt surface with anti-slip material Max. Permissible load: 150 kg (330 lbs.)

Device weight 485 kg (1070 lbs.) ±1%

Gross weight 665 kg (1466 lbs.) ±2%

Shipping box size L: 2.11 m (6.9') W: 1.66 m (5.4') H: 1.07 m (3.5') Volume: 3.74 m³ (132')

Treadmill Speed 0...±7.0 km/h (0... ±2 m/s)

Treadmill perturbation

kinematics

Treadmill Speed:

3...194 cm/s

10...625 cm/s²

Deceleration:

Acceleration:

10...625 cm/s²

Forward Distance:

3...87 cm

Backward Distance:

1...146 cm

Lateral perturbation

kinematics

Speed:

5...60 cm/s

Acceleration:

25...200 cm/s²

Deceleration: Distance:

25...200 cm/s² ±18 cm

Perturbation intensity

30 levels combining Acceleration, Deceleration, Distance, and target speed.

Running belt area

W: 55 cm (21.6") L: 162 cm (63.8")

Walking direction

Forward and Backward

In case of walking direction change, remove buckles from upper bridge hooks, place the person on the opposite side and fasten again the buckles to the same bridge hooks.

Power consumption

Min: 280W Max: 2300W

Stand-by mode

280W

Voltage supply

1 Phase 200V-240V AC L/N/PE 50/60Hz 16A circuit breaker, dedicated line. 3 Phase 200V-240V AC L1/L2/PE 50/60Hz 2x15A circuit breaker, dedicated line.

Electrical outlet

Worldwide According local standards USA

6-20R NEMA

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Motor systemTreadmill:Servo motor, 1.7kW, 3kRPM, 5.9Nm

Perturbation: Servo motor, 0.6kW, 3kRPM, 2.1Nm

Power transmission Treadmill: Gearbox ratio 5:1

Perturbation: Gearbox ratio 5:1

Motor drivers Treadmill: Servo digital drive, CPR 1610W, CC 6.5A, PC 13.0A

Perturbation: Servo digital drive, CPR 1140W, CC 4.0A, PC 8.0A

Electrical safety External isolated transformer: Up to 230v/230v 50/60Hz 2.3kVA Under IEC-60601-1, B-3 UL Recognized, CE.

Leakage current < 0.2mA

Safety power off switch Eme

Safety stop switch

Emergency-off-switch (mains off), switch for immediate disconnection of motor and motor controllers power supply.

Stops lateral perturbation if ranges exceed from maximum of ±21.75 cm

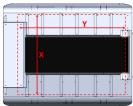
Force sensors Type: Aluminum-Alloy IP65 single point load cell. X4 units

Sensitivity: $2.0 \pm 0.2 \text{ mV/V}$

Force range: 0...250 kg

Location range: X: -65...+65 cm, Y: -80...+80 cm

X: -25"...+25", Y: -31"...+31"



Motion feedback sensors	Device name	<u>Model</u>	Body part	Connection	Technology	<u>Remark</u>	
	IMU	3DT100	Leg (R+L)	Bluetooth	6DOF (Acc & Gyro)	Optional add-on sensors	
Sangara naramatara			COP		IMU		
Sensors parameters			COP		IIVIO		
	Baud Rate [Sample/Sec]		125		125		
	Write to Log	[Sample/Sec]	100		100		
	Service Time [[Hours]	N/A		4		
	Charging current [[mA]	N/A		< 500		
	Operational Indicati	ions	Net & Total I	Load in [Kg]	Connection, Battery le	evel	
Interface	 System power On/Off switch via external isolation transformer with green indication LED PC power On/Off switch with blue indication LED Ethernet connection port: RJ45 10/100/1000 Wireless connection: Bluetooth 4.0 Wi-Fi connection Remote perturbation controller 						
Operator display	Type:	Touch scre	een Projected C	n Projected Capacity technology			
	Characteristics:	Active matrix TFT LCD, 18.5", 16:9, 1366x768, 5ms, 1000:1					
User display	play 24" 16x9 LED display, Stereo built-in speakers, Functional for visual output only.						
Internal computer	Type:	BoxPC					
	Characteristics:	Fanless, Intel Core i5 8th Gen 1.6GHz, 2.5" 128GB SSD Drive, 4G DDR4-2400MHz, Gigabit Ethernet, Intel UHD Graphics 620, Win10 IoT Enterprise 2019 LTSC, DC 12V power input.					
Software	 Touch user interface oriented Perturbation triggered treatments Perturbation intensity scale 1-30 Treatment protocol builder 						

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Patient/Therapist feedback and status data: Treatment parameters, heartrate, gait phase, Load

COP (Center of Pressure) treatments

Treatment row data record and export (to csv format)

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Test condition: A maximum measured value sampled at 1m Euclidian distance around the device.

Self-projection feedback via real time camera

Gait Analysis module (add-on feature)

Safety harness belt

2 supplied sizes: S/M, L/XL

Fall protection support lanyard with height adjustment

Sound Pressure Level

(SPL) Ambient condition

Usage temperature: +10...+40°C

-20 +50°C Storage temperature:

Relative humidity: 30...70 % (non-condensing!)

Atmospheric pressure: 700...1060 hPa

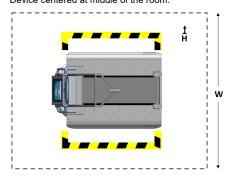
User dimensions

Maximal weight: 135kg (297 lbs.)

Height range: 120cm (47") ... 190cm (75")

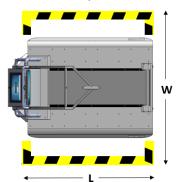
Facilitation

Minimal room dimensions
L: 335cm (132") W: 300cm (120") H: 250cm (99") Device centered at middle of the room.



Keep out zone L: 235cm (93") W: 210cm (83")

To avoid collision at perturbation mode.

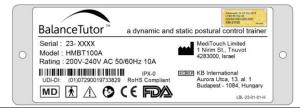


Any floor type, avoid carpet.

Warnings

- No children under the age of six allowed to operate the device or treated without certified personnel.
- It is mandatory to fasten the user with harness to prevent injury cause by a fall.
- The exercise, constantly be supervised by a physiotherapist or a medical doctor in the field of orthopedics and/or
- Patient not allowed to use the BalanceTutor with an open shoes such as sandals. We strongly recommend running shoes.
- Cables and cuffs not allowed for the patients' hands.
- Disregard of warnings and/or the use of the BalanceTutor without a fall protection system is strictly. Prohibited and may lead to accidents and injuries with fatal consequences

Product Label



Product Tracking

Each BalanceTutor device has a manufacturer serial number. Each serial number relates to its production batch.

23-XXXX Running number

Safety & EMC

Directive 93/42/EEC; EN 60601-1; EN 60601-1-1; EN 60601-1-2 (EMC approved); ISO 9001; EN ISO 13485; Emergency-offswitch (mains off), transformer for potential-isolation from the mains under IEC-601-60601-1, B-3 UL Recognized. GMDN® Code 33015

Device Classification

The device is classified as Class I under MDR 2017/745, Annex VIII Chapter 6.

- It has been assessed that Rule 9 is not applicable as perturbation intensities are not hazardous.
 - It has been assessed that Rule 11 does not apply because:
 - The software does not provide information used for diagnostic or therapeutic decisions.
 - The software does not monitor physiological processes
 - The software is intended solely to provide movement ability feedback without clinical interpretation, with all movement ability reference points derived from research data

Conclusion: Under Rule 11 and 13, the BalanceTutor qualifies as a Class I medical device.

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Safety class / category

Class I Medical device

Classification

MDR 2017/745 Annex VIII

Manufacturer

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